FIBER

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HL-C1

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MICRO PHOTOELECTRIC SENSORS ARFA SENSORS SAFFTY COMPONENTS PRESSURE SENSORS INDUCTIVE PROXIMIT SENSORS PARTICULAR USE SENSORS

SENSORS

PHOTOELECTRIC

Ultra High-speed Laser Displacement Sensor CCD Style SERIES



General terms and conditions...... P.1 Glossary of terms / General precautions..P.1019 / P.1027

Sensor selection guideP.11~ / P.833~ About laser beam.....P.1025~



This product is classified as a Class 1 / Class 2 / Class 3B Laser Product in IEC / JIS standards and a Class I / Class II / Class IIIb Laser product in FDA regulations. Never look at or touch the direct laser beam and its reflection.

FDA

forming to regulation

High speed of 100 µs, Ultra high-speed & stable measurement for a variety of measurement objects

100 µs, fast sampling rate

Resolution of 1 µm 0.039 mil, linearity of ±0.1 % F.S.

Ultra high-speed sampling of 100 µs has now been achieved. Thus enabling ultra high-speed measurement of rotating, vibrating and moving objects.

Now available with ultra-precise 1 µm 0.039 mil resolution measurement capability (HL-C105) and a linearity of ±0.1 % F.S. (for all models).

High accuracy measurement is now possible, unaffected by the surface condition of the detected object

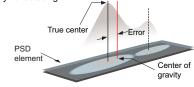
All deficiencies inherent in the conventional PSD sensing method have now been solved. Whereas the PSD method measures position information from the center of gravity of the total light quantity distribution of the light spots connected along each light element, the linear image sensing method measures the peak position values for the light spots themselves. This advance now makes high-precision measurement possible, regardless of the surface condition of the object whether for metal hairline surface cracks or for non-reflective surfaces, e.g. black rubber.

Principle For detection of a V-shaped groove Change in measurement data due to color difference (White ceramic / Black rubber) As the sensor measures the peak position of the light age sensor method> HL-C108B-BK(linear image sensor method) PSD method <PSD method>



spot, it is not affected by secondary reflected light, resulting in no error. True center Image sensor element

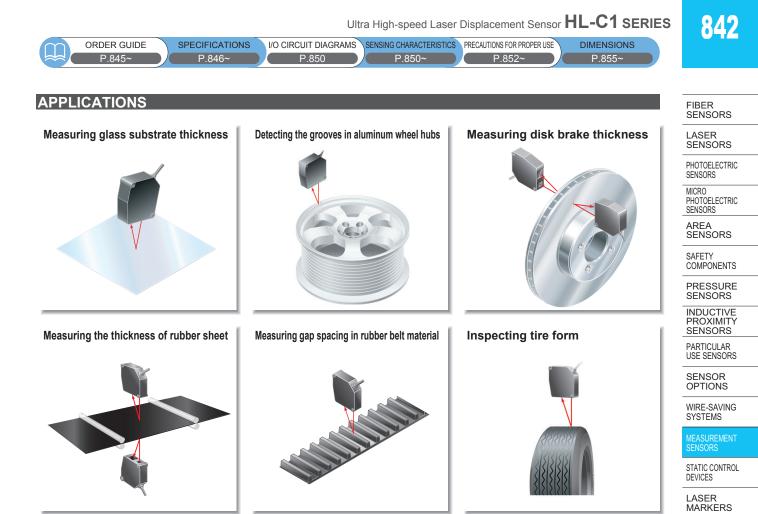
As the sensor measures the center of gravity for the light quantity distribution of the entire beam spot as position information, errors occur due to the presence of secondary reflected light.



FDA regulations conforming types are available

FDA regulations conforming types, most suitable for equipment used in the USA, are now available.





The long and wide range

Measures wide changes over long ranges

The long and wide range capabilities over $350 \text{ mm} \pm 200 \text{ mm} 13.780 \text{ in} \pm 7.874 \text{ in}$ allow large changes to be measured. Even if the object position changes, there is no need to change the sensor head settings or position.

High speed and high precision even over long and wide ranges with an ultra-small type head

High-speed and high-precision performance has been achieved in an ultra-small head of W26.6 × H82 × D87 mm W1.047 × H3.228 × D3.425 in with high-speed sampling of 100 μ s at a resolution of 10 μ m 0.394 mil, and a linearity of ±0.1 % F.S.



Sensor heads HL-C135C-BK10 Controller HL-C1C-M-WL

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Products



2 sensor heads can be connected! Reduces costs and saves space

The controller, to which 2 sensor heads can be connected, incorporates 2 separate input / output channels.

This feature saves the expense and space usually required by a second controller, whenever 2 sensor heads are used.

Waterproof sensor head construction, compliant with IP67 rated protection

The **HL-C1** series can withstand water splashes.



Note: Accurate measurement cannot be performed if water is present on the sensing window of the sensor head itself.

Touch panel operation, easy and compact

A variety of setting and measurement data can be displayed easily. (Optional)

Easy maintenance with sensor head compatibility

Maintainability has been significantly improved. Compatibility has been achieved through the incorporation of correction data into the sensor heads themselves. This new sensor series no longer needs the amount of maintenance usually required for conventional displacement sensors of this class.

SUNX

Magnetic Displacement

GP-X

GP-A

HL-T1

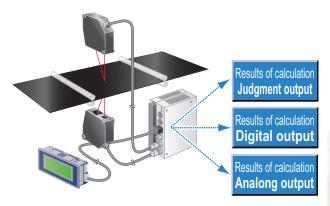
LA-300

LA Other Products

Collimated Beam Sensors

Calculations can be performed when 2 sensor heads are used

The built-in calculation function allows for the measurement of gaps and thicknesses without requiring a digital panel controller, thus saving further on costs and space.



Controller compact and front connection reduces setup space

The ultra-compact controller **HL-C1C-M** with dimensions of W40 × H120 × D74 mm W1.575 × H4.724 × D2.913 in requires much less space for installation. Adhesive installation is also possible. Furthermore, the cables can be connected directly or to a removable terminal board, so that all connections come from the same direction in order to further save space.

40 mm (HL-C1C-M-W: 60mm 2.362 in)



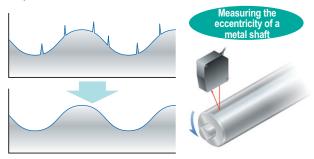
Enhanced functionality

The **HL-C1** series incorporates myriad useful functions, including hold functions, calculation functions, filter functions and a hysteresis-setting function, that facilitate convenient usage in a variety of diverse applications.

Low-pass / High-pass filter functions

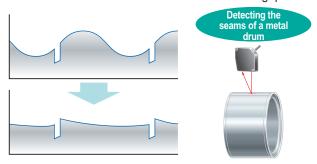
<Low-pass filter function>

For example, if the surface conditions of a metal object cause noise that interferes with accurate measurement, the use of the low-pass filter function will reduce the effects of noise and allow for the stable measurement of displacement.



<High-pass filter function>

When measuring seams and gaps in objects that undergo large displacement changes due to vibration or tilting, such as measuring the eccentricity of a rotating object, this function will minimize the effects of these undulations and enable the accurate measurement of seams and gaps.



Analog output switching function during alarm output

During measurement, if the unit becomes incapable of performing measurements due to excessive or insufficient incident light intensity (during alarm output), this function allows the analog output to be switched to either hold the data sensed just previously, or to output a fixed value. If the fixed value is selected, one of two options can be chosen for the analog output during alarm output: the output of the maximum value (voltage output: +10.9 V, current output: 29.5 mA) or the output of the minimum value (voltage output: -10.9 V, current output: -10.9 V, current output: -10.9 V, current output: 0 mA).

	Maximum analog output value The analog output can be used to confirm whether or not the unit is capable of performing measurements.
Amount of displacement	
of dis	Data hold from previous measurement
unto	This function can be used when the effect of the hole must be ignored.
₽ I	the hole must be ignored.
Т	'ime

Hold functions

The HL-C1 series incorporates 4 hold modes.

NORM (no hold)	This mode outputs the amount of displacement from the measurement center distance, in real time. This mode is utilized for general-purpose operation.
P-P	This mode holds the output at the difference between the maximum and minimum measured values. This mode is utilized for vibration or eccentricity measurements.
PEAK	This mode holds the output at the maximum measured value.
VALLEY	This mode holds the output at the minimum measured value.

Data buffering function

It is possible to accumulate data up to 48,000 data into a controller temporarily in order to capture measurement data into a PC. All the accumulated data can be captured into the PC with **HL-C1AiM**. Used for reading and storing all data including the verification of measurement data when introduced as well as all post-measurement data.

FIBER SENSORS

LASER SENSORS

PHOTOELECTRIC SENSORS

MICRO

PHOTOELECTRIC SENSORS

AREA SENSORS

SAFETY COMPONENTS

PRESSURE SENSORS

PROXIMITY

PARTICULAR USE SENSORS

SENSOR OPTIONS

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EASUREMENT

STATIC CONTROL DEVICES

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	GP-A Collimated Beam Sensors
	Collimated
	Collimated Beam Sensors
	Collimated Beam Sensors HL-T1
	Collimated Beam Sensors HL-T1 LA-300

SUNX)

LA-300

Othe Products

ORDER GUIDE

Sensor heads

LASER SENSORS	Ser	ISO	r heads							
PHOTO- ELECTRIC SENSORS	Ту	ре	Appearance	Measurement center distance	Resolution (Note 1, 2)	Beam diameter	Model No.	Applicable controller	Applicable console	Conforming standards / regulations
MICRO PHOTO- ELECTRIC SENSORS		range			10 µm	400 × 200 µm				IEC / JIS
AREA SENSORS	type	Wide r	*	350 mm 13.780 in (Measuring range ±200 mm 7.874 in)	0.394 mil	15.748 × 7.874 mil approx.	HL-C135C-BK10	HL-C1C-M-WL	HL-C1DP-E-WL	/ FDA
SAFETY COMPONENTS	lective	urpose			2 µm	100 × 140 µm	HL-C108B-BK			IEC / JIS
PRESSURE SENSORS	Diffuse reflective type	precision General purpose		85 mm 3.346 in (Measuring range ±20 mm 0.787 in)	0.079 mil	3.937 × 5.512 mil approx.	HL-C108F-BK			FDA / IEC / JIS
INDUCTIVE PROXIMITY SENSORS	Diff	ecision			1 µm	70 × 120 µm	HL-C105B-BK			IEC / JIS
PARTICULAR USE SENSORS		High		50 mm 1.969 in (Measuring range ±5 mm 0.197 in)	0.039 mil	2.756 × 4.724 mil approx.	HL-C105F-BK			FDA / IEC / JIS
SENSOR	ype	purpose	*		2 µm	100 × 140 μm	HL-C108B	HL-C1C-M	HL-C1DP-E	IEC / JIS
WIRE- SAVING SYSTEMS	Specular reflective type	General purpose		81.4 mm 3.205 in (Measuring range ±16 mm 0.630 in)	0.079 mil	3.937 × 5.512 mil approx.	HL-C108F			FDA / IEC / JIS
MEASURE- MENT SENSORS	cular ref	High precision			1 µm	70 × 120 µm	HL-C105B			IEC / JIS
STATIC CONTROL DEVICES	STATIC NTROL EVICES			46 mm 1.811 in (Measuring range ±4 mm 0.157 in)	0.039 mil	2.756 × 4.724 mil approx.	HL-C105F			FDA / IEC / JIS
LASER MARKERS	Note	s: 1)	These values were obtained by	converting P-P values into a	a distance.	The P-P values inc	dicate the distributi	on of measured v	alues throughout	the

Notes: 1) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance.

These values were obtained with an average number of samples: 256, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).

Controllers

	Туре	Appearance	Model No.	Judgment outputs
Selection Guide Laser Displacement HL-C2 HL-C1 LM10	Standard		HL-C1C-M	Photo-MOS relay
Magnetic Displacement GP-X GP-A Collimated Beam Sensors HL-T1	For HL-C135C-BK10		HL-C1C-M-WL	FILOLO-WOS Telay

Compact consoles

LA Other ducts	Туре	Appearance	Model No.	
	Standard		HL-C1DP-E	
	For HL-C1C-M-WL		HL-C1DP-E-WL	

SUNX

ORDER GUIDE

Sensor head extension cable

Sensor head extension cal	nead extension cable				
Appearance	Model No.	Description		PHOTO- ELECTRIC SENSORS	
	HL-C1CCJ2	Length: 2 m 6.562 ft Net weight: 160 g approx.		MICRO PHOTO- ELECTRIC SENSORS	
	HL-C1CCJ5	Length: 5 m 16.404 ft Net weight: 350 g approx.	Cabtyre cable with connector on both ends	ELECTRIC SENSORS	
	HL-C1CCJ10	Length: 10 m 32.808 ft Net weight: 700 g approx.	Cable outer diameter: ø7 mm ø0.276 in Connector outer diameter: ø14.7 mm	AREA SENSORS	
	HL-C1CCJ20 Length: 20 m 65.617 ft Net weight: 1,400 g approx. Ø0.579 in max.	ø0.579 in max.	SAFETY		
	HL-C1CCJ30	Length: 30 m 98.425 ft Net weight: 2,000 g approx.		COMPONENTS	

Intelligent monitor

Appearance	Model No.	Description	INDUCTIVE PROXIMITY SENSORS
Intelligent Monitor HL-CIAM			PARTICULAR USE SENSORS
Advanced Executional Monitor	HL-C1AiM	Enables the waveform display of each measurement condition setting and of measurement value as well as monitoring of measurement data and received light intensity data. 1pc. of COM port connecting cable which is made by Matsushita Electric Works, Ltd. is attached.	SENSOR OPTIONS
		The of composition connecting caple which is made by massishing Electric works, Ed. is attached.	WIRE- SAVING SYSTEMS

SPECIFICATIONS

Sensor heads

\mathbb{N}	_	Diffuse reflective type				
	Туре	Wide range	General purpose	High precision		
	EC / JIS standards conforming type		HL-C108B-BK	HL-C105B-BK		
Item	Image: Standards conforming type Image: Standards conforming type Image: Standards conforming type Image: Standards conforming type	HL-C135C-BK10	HL-C108F-BK	HL-C105F-BK		
Mea	surement center distance	350 mm 13.780 in	85 mm 3.346 in	50 mm 1.969 in		
Mea	suring range	±200 mm 7.874 in	±20 mm ±0.787 in	±5 mm ±0.197 in		
Res	olution (Note 2, 3)	10 µm 0.394 mil	2 µm 0.079 mil	1 µm 0.039 mil		
Line	arity (Note 4)		±0.1 % F.S.			
Tem	perature characteristics		0.02 % F.S./°C		Selection Guide	
Lase	er emission indicator	Green LED (lights u	up during laser emission or immediately bef	ore laser emission)	Laser	
Mea	suring range indicator	Yellow LED [blinks within the m	easuring range and lights up when near the	e measurement center distance]	Displacement	
	Pollution degree		3 (Industrial environment)		HL-C2	
Environmental resistance	Protection	IP67 (IEC)(exclu	ding the connector) (Refer to p.984 for deta	ils of standards.)	HL-C1	
ista	Ambient temperature	0 to +45 °C +32 to +113 °F (No dew condensation), Storage: -20 to +70 °C -4 to +158 °F			LM10	
res	Ambient humidity		35 to 85 % RH, Storage: 35 to 85 % RH	ge: 35 to 85 % RH		
ntal	Ambient illuminance	Incandescent light: 3,000 tx at the light-receiving face				
amr	Voltage withstandability	500 V AC for one min. betwee	n the exclusive controller power input part a	and the sensor head enclosure	GP-X	
/iror	Insulation resistance	20 M Ω , or more, with 500 V DC megge	r between the exclusive controller power in	put part and the sensor head enclosure	GP-A	
ЕŊ	Vibration resistance	10 to 55 Hz (period: 1 min.) frequency, 1.5 mm 0.059 in amplitude in X,Y and Z directions for two hours each			Collimated Beam Sensors	
	Shock resistance	196 m/s² accelerati	on (20 G approx.) in X,Y and Z directions for	or three times each	HL-T1	
_			Red semiconductor laser, Class 2 (Class I	I for FDA regulations)	LA-300	
Emit	ting element	for FDA regulations) (Max. output: 10 mW, Peak emission wavelength: 658 nm 0.026 mil)	(IEC / JIS standards conforming type: IEC FDA / IEC / JIS) (Max. output: 1 mW, Peal	k omission wavelength: 658 nm 0 026 mil)		
Bea	n diameter (Note 5)	$400 \times 200 \ \mu\text{m} \ 15.748 \times 7.874 \ \text{mil} \ \text{approx}.$	$100 \times 140 \ \mu\text{m} \ 3.937 \times 5.512 \ \text{mil approx}.$	$70 \times 120 \ \mu\text{m} \ 2.756 \times 4.724 \ \text{mil} \ \text{approx}.$	LA	
-	eiving element	Linear image sensor			Other Products	
	osure earthing	Floating				
Material Enclosure: Die-cast aluminum, Case cover: Die-cast aluminum, Front cover				. Front cover: Glass		
Cable Cabtyre cable, 0.5 m 1.640 ft long with connector						
Cable extension Extension up to total 30 m 98.425 ft is possible, with optional cable.						
Weig	pht		Net weight: 300 g approx.			
Acce	essory	English warning label: 1 set [The FDA regulations co	onforming type includes a set of both the IEC label (wr	itten in English) and JIS label (written in Japanese)].		

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256 (HL-C135C-BK10: 512), measurement center distance, object measured is made of white ceramic (an aluminum vapor deposition surface reflection mirror was used with specular reflective type). Linearity also depends upon the characteristics of the object being measured.

2) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance. 3) These values were obtained with an average number of samples: 256 (HL-C135C-BK10: 512), when using an object made of our company's standard

white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types). 4) This value indicates the range of errors for an ideal linear displacement output, when using an object made of our company's standard white ceramic for measurement (an

aluminum vapor deposition surface reflection mirror was used with specular reflective types). This value may fluctuate depending on the characteristics of the object measured. 5) These values were defined by using 1/e² (13.5 %) of the center light intensity. If there is a slight leakage of light outside the normal spot diameter and if the periphery surrounding the sensing point has a higher reflectivity than the sensing point itself, then the results may be affected. SUND

FIBER SENSORS

PRESSURE SENSORS

STATIC CONTROL DEVICES

SPECIFICATIONS

Sensor heads

-	\mathbb{N}	-	Specular re	flective type	
S	Туре		General purpose	High precision	
0)-000		IEC / JIS standards conforming type FDA regulations	HL-C108B	HL-C105B	
A S	Item	FDA regulations conforming type	HL-C108F	HL-C105F	
γ	Mea	surement center distance	81.4 mm 3.205 in	46 mm 1.811 in	
S	Mea	suring range	±16 mm ±0.630 in	±4 mm ±0.157 in	
E S	Reso	olution (Note 2, 3)	2 µm 0.079 mil	1 µm 0.039 mil	
 E	Linea	arity (Note 4)	±0.1 9	% F.S.	
Y S	Tem	perature characteristics	0.02 %	F.S./°C	
R	Lase	er emission indicator	Green LED (lights up during laser emissi	on or immediately before laser emission)	
<u>S</u>	Mea	suring range indicator	Yellow LED [blinks within the measuring range and line	ghts up when near the measurement center distance]	
R S		Pollution degree	3 (Industrial	environment)	
-	Protection		IP67 (IEC) (excluding the connector) (Refer to p.984 for details of standards.)		
G S	Ambient temperature Ambient humidity Ambient illuminance Voltage withstandability Insulation resistance		0 to +45 °C +32 to +113 °F (No dew condensation), Storage: –20 to +70 °C -4 to +158 °F		
T S	resis	Ambient humidity	35 to 85 % RH, Stor	rage: 35 to 85 % RH	
0	ental	Ambient illuminance	Incandescent light: 3,000 &	x at the light-receiving face	
L S	nme	Voltage withstandability	500 V AC for one min. between the exclusive control	ller power input part and the sensor head enclosure	
R S	inviro	Insulation resistance	20 M Ω , or more, with 500 V DC megger between the exclusi	ve controller power input part and the sensor head enclosu	
_	ш	Vibration resistance	10 to 55 Hz (period: 1 min.) frequency, 1.5 mm 0.059 i	n amplitude in X,Y and Z directions for two hours each	
		Shock resistance	196 m/s ² acceleration (20 G approx.) in 2	X,Y and Z directions for three times each	
	Emit	ting element	Red semiconductor laser, Class 2 (Class II for FDA regulat FDA regulations conforming type: FDA / IEC / JIS) (Max. or		
	Bear	m diameter (Note 5)	100 × 140 μm 3.937 × 5.512 mil approx.	70 × 120 μm 2.756 × 4.724 mil approx.	
	Rece	eiving element	Linear ima	ige sensor	
_	Encl	osure earthing	Floa	ating	
n Ə	Mate	erial	Enclosure: Die-cast aluminum, Case cov	er: Die-cast aluminum, Front cover: Glass	
er ht	Cabl	e	Cabtyre cable, 0.5 m 1.6	40 ft long with connector	
2	Cabl	e extension	Extension up to total 30 m 98.425	ft is possible, with optional cable.	
1	Weig	ght	Net weight: 3	300 g approx.	
)	Acce	essory	English warning label: 1 set [The FDA regulations conforming type includes a s	et of both the IEC label (written in English) and JIS label (written in Japar	

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256, measurement center distance, object measured is made of white ceramic (an aluminum vapor deposition surface reflection mirror was used with specular reflective type). Linearity also depends upon the characteristics of the object being measured.

2) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance.

3) These values were obtained with an average number of samples: 256, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).

4) This value indicates the range of errors for an ideal linear displacement output, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types). This value may fluctuate depending on the characteristics of the object measured.

5) These values were defined by using 1/e² (13.5 %) of the center light intensity. If there is a slight leakage of light outside the normal spot diameter and if the periphery surrounding the sensing point has a higher reflectivity than the sensing point itself, then the results may be affected.

GP-X

GP-A

Collimated Beam Sensors

HL-T1

LA-300

Other Products

LA

SPECIFICATIONS

ontrollers				
<u></u>	Photo-MQS	relay output		
Туре	Stardard	For HL-C135C-BK10		
em Model No.	HL-C1C-M	HL-C1C-M-WL		
connection sensor heads		sensor heads		
upply voltage		ding ripple 0.5 V (P-P)		
urrent consumption		When 2 sensors are connected: 550 mA approx.		
ampling rate	Selectable from 100 µs / 144 µs / 200	μs / 255 μs / 332 μs / 498 μs / 1,000 μs		
emperature characteristics	±0.01 %	⊳ F.S./°C		
Voltage	Output voltage: ±5 V/F.S. [default setting wh Output range: –10.9 to +10.9 V Output current: Max. 2 mA, Output impedan	en diffuse reflective mode is selected (Note 2)] ce: 50 Ω		
Voltage	Output current: 4 to 20 mA/F.S. [default setting v Output range: 0 to 29.5 mA (maximum of 25 mA Load impedance: 250 Ω or less	vhen diffuse reflective mode is selected (Note 4)] at max. load impedance)		
larm output	Photo-MOS relay • Maximum load current: 50 mA • Applied voltage: 30 V DC or less • ON impedance: 35 Ω or less • Operation time: Max. 2 ms	(between alarm output and COM)		
Output operation	Opened when the amount of I	ght is excessive or insufficient.		
Short-circuit protection	Incorp	orated		
udgment outputs D1, O2)	Photo-MOS relay • Maximum load current: 50 mA • Applied voltage: 30 V DC or less • ON impedance: 35 Ω or less • Operation time: Max. 2 ms	 Photo-MOS relay Maximum load current: 50 mA Applied voltage: 30 V DC or less (between judgment output and COM) ON impedance: 35 Ω or less 		
Utilization category	DC-12 0	or DC-13		
Output operation	Opened or closed when the threshold value is reached. Determined based on judgment output mode selection. (The threshold value varies with the hysteresis setting.)			
Short-circuit protection	Incorp	orated		
erial input / output	RS-232C			
ming input aser emission)	Laser emission stops or continues when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input or there is an open circuit: determined based on input mode selection.			
emote interlock input		Laser emission stop when open circuit		
ero set ON input	Zero set: ON when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input			
ero set OFF input	Zero set: OFF when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input			
Laser emission	Green LED (lights up during laser emission from sensor head 1 or sensor head 2, or immediately before laser emission)			
BRIGHT	Red LED (lights up upon disabled measurement due to excessive light at sensor head 1 or 2)			
Laser emission BRIGHT DARK	Red LED (lights up upon disabled measureme	nt due to insufficient light at sensor head 1 or 2)		
etting / Data display	Compact con	sole (optional)		
🙃 Shift	±20.0000 mm ±0.787 in	±200.0000 mm ±7.874 in		
Gradient Span	0.9000 t	o 1.1000		
erage number of samples (Note 5)	OFF, 2 to 32,768	3 times (16 steps)		
igital filters (Note 5)	High pass: OFF, 10 to 2,000 Hz (9 steps)	, Low pass: OFF, 10 to 2,000 Hz (9 steps)		
alculation functions (Note 5)	L ± KA, L ± KB, L ± K (A ± B) A, B: Sensor head 1, Sensor head 2 measurement values, L = ±999.9999, K = 0.0001 to 99.9999			
old functions (Note 5)	Selectable from NORMA	L / P-P / PEAK / VALLEY		
Pollution degree	environment)			
Ambient temperature		sation), Storage: -20 to +70 °C -4 to +158 °F		
Ambient humidity	35 to 85 % RH, Sto	rage: 35 to 85 % RH		
Voltage withstandability	500 V AC for one min. between	power input part and enclosure		
Insulation resistance	20 MΩ, or more, with 500 V DC megger	between power input part and enclosure		
Pollution degree Ambient temperature Ambient humidity Voltage withstandability Insulation resistance Vibration resistance Shock resistance	10 to 55 Hz frequency (period: 1 min.) 0.75 mm 0.030	in amplitude in X,Y and Z directions for 30 min. each		
Shock resistance	196 m/s² (20 G approx.) in X, Y	and Z directions for 3 times each		
able length	Power line: Less than 10 m 32.808 ft	Signal line: Less than 30 m 98.425 ft		
/eight	Net weight: 3	300 g approx.		
ccessory	1	Key: 2 pcs.		

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256 (HL-C1C-M-WL: 512), and measurement center distance.

2) If specular reflective mode is selected, then the default setting is ±4 V/F.S.

3) The maximum analog output current will vary with load impedance.

4) If specular reflective mode is selected, then the default setting is 5.6 to 18.4 mA/F.S.

5) These values can be set using the command input from external equipment via the compact console and RS-232C interface.

FIBER SENSORS

LASER SENSORS

PHOTO-ELECTRIC SENSORS

MICRO PHOTO-ELECTRIC SENSORS

AREA SENSORS

SAFETY COMPONENTS

PRESSURE SENSORS

INDUCTIVE PROXIMITY SENSORS PARTICULAR USE SENSORS SENSOR OPTIONS

WIRE-SAVING SYSTEMS

STATIC CONTROL DEVICES

LASER MARKERS

SPECIFICATIONS

Compact console

\swarrow	Туре	Standard	For HL-C1C-M-WL				
Item	Model No.	HL-C1DP-E	HL-C1DP-E-WL				
Supp	bly voltage	24 V DC ± 10 % including ripple 0.5 V (P-P)					
Curr	ent consumption	200 mA or less					
	Display element	STN monoc	STN monochrome LCD				
Display	Back light	Green LED					
Disp	Lifetime of LCD	Average 50,000 hours (Note 2)					
	Display range	-99.9999 to 99.9999					
Touch panel	Operation force	0.98 N or less					
Tou	Lifetime	1,000,000 times or more					
e	Protection	IP65 (IEC) (in initial state) (Note 3) Dust proof and drip proof only at front face of panel. (Waterproof packing is used for surfaces in contact with panel.)					
Environmental resistance	Ambient temperature	0 to +40 °C +32 to +104 °F (No dew condensation), Storage: –20 to +60 °C –4 to +140 °F					
l res	Ambient humidity	20 to 85 % RH, Storage: 10 to 85 % RH					
ienta	Superimposed noise resistance	1,000 V (P-P) or more, pulse width 50 ns and 1 μs between power terminals					
ronm	Electrostatic noise resistance	5,000 V or more (surface of panel)					
_	Vibration resistance	10 to 55 Hz frequency, 0.75 mm 0.030 in amplitude in X, Y and Z directions for 10 min. each					
	Shock resistance	98 m/s ² acceleration (10 G approx.) in X, Y and Z directions for four times each					
Weig	ıht	Net weight: 260 g approx.					
Accessory		Connecting cable for connecting the controller to the console: 1 pc.					

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +20 °C +68 °F. 2) This value indicates the average lifetime of the unit when used under a normal temperature of +25 °C +77 °F.

3) When reinstalling the console, replace the waterproof packing.

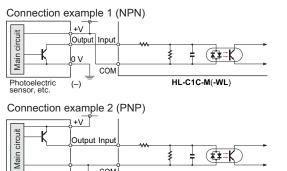
I/O CIRCUIT AND WIRING DIAGRAMS

HL-C1C-M(-WL)

Photoelectric sensor, etc.

I

Input circuit diagram

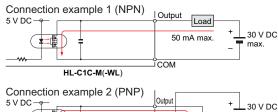


HL-C1C-M(-WL)

COM

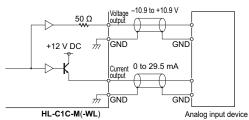
Output	circuit	diagram	
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Alarm output, Judgment output



5 V DC 50 mA max. L, Load COM HL-C1C-M(-WL)

Analog output diagram



Notes: 1) Do not short-circuit analog output terminals or apply vottage to them. 2) Use shielded wires for analog outputs.

Terminal arrangement

Input terminals				
	Symbol	Description		
	TM1 (Note 1)	Timing input (sensor head 1) (Note 1)		
111	111	Zero set ON input (sensor head 1)		
	112	Zero set OFF input (sensor head 1)		
	COM	Input common		
121	TM2 (Note 2)	Timing input (sensor head 2) (Note 2)		
122	121	Zero set ON input (sensor head 2)		
	122	Zero set OFF input (sensor head 2)		
	COM	Input common		
	•	Not used		
	•	Not used		
	•	Not used		
「⁺∥ ЦЩ	•	Not used		
	•	Not used		
	+	24 V DC input for power supply		
	-	Power supply ground		
	æ	Function ground		

Itput terminals	Symbol	Description			
	AL1	Alarm output (sensor head 1)			
011	O11	Judgment output 1 (sensor head 1)			
012	O12	Judgment output 2 (sensor head 1)			
	COM	Output common			
021	AL2	Alarm output (sensor head 2)			
022	O21	Judgment output 1 (sensor head 2)			
	O22	Judgment output 2 (sensor head 2)			
	COM	Output common			
	•	Not used			
	•	Not used			
	V1	Analog voltage output (sensor head 1)			
	1	Analog current output (sensor head 1)			
	GND	Analog output ground			
	V2	Analog voltage output (sensor head 2)			
	12	Analog current output (sensor head 2)			
	GND	Analog output ground			

Notes: 1) In the case of HL-C1C-M-WL, "IL1: Remote interlock input (sensor head 1)"

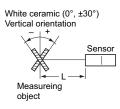
2) In the case of HL-C1C-M-WL, "IL2: Remote interlock input (sensor head 2)'

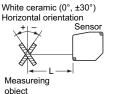
3) Terminals marked with "•" are not used. Some are connected to internal circuitry and cannot be used as relay terminals in wiring, etc.

SENSING CHARACTERISTICS(TYPICAL)

HL-C135C-BK10

Correlation between measuring distance and error characteristics





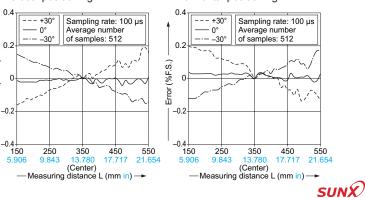
· Vertical positioning

Error (%F.S.)

Ou

· Horizontal positioning

Diffuse reflective type



max.

850

FIBER SENSORS

WIRE-SAVING SYSTEMS STATIC CONTROL DEVICES LASER MARKERS

HL-C2 HL-C1 LM10 Magnetic Displacem GP-X GP-A Collimated Beam Senso

Selection Guide

HL-T1 LA-300

LA Other Product

FIBER SENSORS LASER SENSORS PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS AREA SENSORS

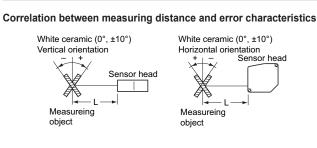


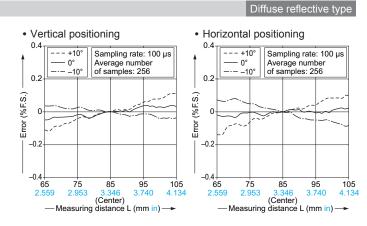
STATIC

CONTROL DEVICES LASER MARKERS



HL-C108D-BK





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HL-C105D-BK

White ceramic (0°, ±10°)

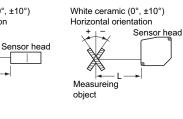
Vertical orientation

Å

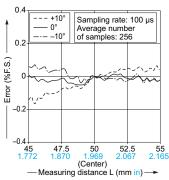
object

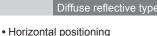
Measureing

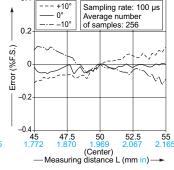
Correlation between measuring distance and error characteristics



Vertical positioning







HL-C108B HL-C108F

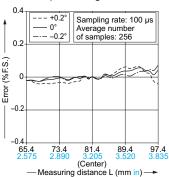
Correlation between measuring distance and error characteristics Selection Guide Aluminum vapor deposition Aluminum vapor deposition surface reflection mirror surface reflection mirror (0°, ±0.2°) (0°, ±0.1°) HL-C2 Vertical orientation Horizontal orientation Sensor head Sensor head

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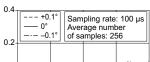
object

Measureing

Vertical positioning



Specular reflective type



81.4

(Center)

Measuring distance L (mm in)

Specular reflective type

89.4

97.4 3.835

50 1.960

48

· Horizontal positioning

73.4

Error (%F.S.)

0

-0.:

-0

65.4

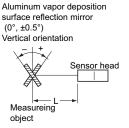
HL-C1 LM10 Magnetic splacement GP-X GP-A Collimated Beam Sensors HL-T1 LA-300 LA Other Products

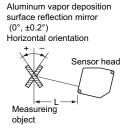
HL-C105B HL-C105F

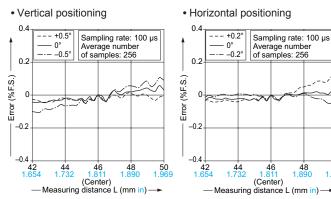
Measureing

object

Correlation between measuring distance and error characteristics









LASER SENSORS

PHOTO-ELECTRIC

SENSORS

MICRO PHOTO-ELECTRI SENSOR

ARFA

SENSOR OPTIONS

WIRE-SAVING SYSTEMS

STATIC CONTROL DEVICES LASER MARKERS

Selection Guide

HL-C2

HL-C1

Magnetic Displaceme

GP-X

GP-A

Collimated Beam Senso

HL-T1 LA-300

LA Other Products

PRECAUTIONS FOR PROPER USE

• This catalog is a guide to select a suitable product. Be sure to read instruction manual attached to the product prior to its use.

• Never use this product as a sensing device for personnel protection.

- In case of using sensing devices for personnel protection, use products which meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.
- HL-C108 HL-C105 HL-C105 HL-C105 HL-C105 HL-C105 HLaser Product in FDA regulations. Do not look at the laser beam directly or through optical system such as a lens.
 - The following label is attached to the product. Handle the product according to the instruction given on the warning label.



(The English warning label based on FDA regulations is pasted on the FDA regulations conforming type.)

(The English warning label is packed with the sensor)

- HLC135C-BK10 This product is classified as a Class 3B Laser Product in IEC / JIS standards Class IIIb. Never look at or touch the direct laser beam and its reflection.
 - The following label is attached to the product. Handle the product according to the instruction given on the warning label.



The English warning label based on FDA regulations is pasted on the FDA regulations conforming type.

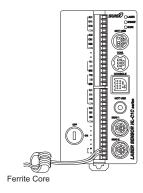
(The English warning label is packed with the sensor)

To comply with the European EMC Directive (HL-C1C-M-WL)

• To comply with the European EMC Directive, install a ferrite core on wires to the terminal block as shown below.

Recommended ferrite core:

E04RC281613 manufactured by Seiwa Electric Mfg. Co., Ltd or equivalent

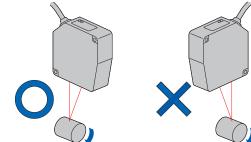


Refer to p.1027 for general precautions and p.1025~ for laser beam. FIBER SENSORS

Sensor head mounting direction

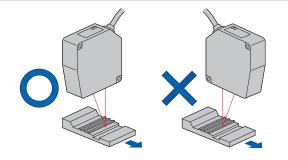
• To obtain the greatest precision, the sensor head should be oriented facing the direction of movement of the object's surface, as shown in the figure below.

Rotating object



SENSORS SAFETY COMPONENTS PRESSURE SENSORS INDUCTIVE PROXIMITY SENSORS PARTICULAR USE SENSORS

Object that has large differences in gaps, grooves and colors



Safety standards for laser beam products

Classification by IEC 60825-1: 2001

Classification	Description
Class 1	Lasers that are safe under reasonably foreseeable conditions of operation, including the use of optical instruments for intrabeam viewing.
Class 1M	Lasers emitting in the wavelength range from 302.5 nm to 4,000 nm which are safe under reasonably foreseeable conditions of operation, but may be hazardous if the user employs optics within the beam.
Class 2	Lasers that emit visible radiation in the wavelength range from 400 nm to 700 nm where eye protection is normally afforded by aversion responses, including the blink reflex. This reaction may be expected to provide adequate protection under reasonably foreseeable conditions of operation including the use of optical instruments for intrabeam viewing.
Class 2M	Lasers that emit visible radiation in the wavelength range from 400 nm to 700 nm where eye protection is normally afforded by aversion responses, including the blink reflex. However, viewing of the output may be more hazardous if the user employs optics within the beam.
Class 3R	Lasers that emit in the wavelength range from 302.5 nm to 10 ⁶ nm where direct intrabeam viewing is potentially hazardous but the risk is lower than for Class 3B lasers, and fewer manufacturing requirements and control measures for the user apply than for Class 3B lasers.
Class 3B	Lasers that are normally hazardous when direct intrabeam exposure occurs (i.e. within the NOHD). Viewing diffuse reflections is normally safe.
Class 4	Lasers that are also capable of producing hazardous diffuse reflections. They may cause skin injuries and could also constitute a fire hazard.

HL-C LM1 Magne Displaceme

Collima Beam Sens

HL-T1

LA-300

Other Products

LA

PRECAUTIONS FOR PROPER USE

Safe use of laser products

· For the purpose of preventing users from suffering injuries by laser products, IEC 60825-1: 2001 (JIS C 6802: 2005) (Safety of laser products). Kindly check the standards before use.

Summary of user precautions IEC 60825-1: 2001 (JIS C 6802: 2005)

* Quoted from Safety of laser products, Annex Table D. 3

SAFETY COMPONENTS		Classification						
	Requirements subclause							
PRESSURE SENSORS	Subciause	Class 1	Class 1M	Class 2	Class 2M	Class 3R	Class 3B	Class 4
INDUCTIVE PROXIMITY SENSORS PARTICULAR USE SENSORS	Laser safety officer	Not required but recommended for applications that involve direct			emission Required for non-visible	Required		
SENSOR OPTIONS	Remote interlock		Ν	ot require	ed		Connect or door o	
WIRE- SAVING SYSTEMS	Key control		Ν	ot require	ed		Remove when no	
MEASURE- MENT SENSORS	Beam attenuator		N	ot require	ed		When in use prevents inadvertent exposure	
STATIC CONTROL DEVICES LASER MARKERS	Emission indicator device	indicates laser is energized for non-visible wavelengths			Indicates laser is energized			
	Warning signs	Not required			Follow pro			
	Beam path	Not required	Class 1M (Note 1) as for Class 3B	Not required	Class 2M (Note 2) as for Class 3B		erminate beam at end useful length	
Selection Guide	Specular reflection	No requirements	Class 1M (Note 1) as for Class 3B	No requirements	Class 2M (Note 2) as for Class 3B	Prevent unintentional reflections		
Laser Displacement HL-C2 HL-C1 LM10	Eye protection		No	o requirements procedures practicable MPE exceed			ring and trative res not ble and	
Magnetic Displacement GP-X	Protective clothing	No requirements Sometimes Specific required			Specific requirements			
GP-A Collimated Beam Sensors	Training	No requirements Class 3R (Note 1) as for Class 3R No requirements Class 2M (Note 2) as for class 3R R Required for all o and maintenance personnel						
111 74	Notes: 1) Class 1M laser products that failed condition 1 of table 10							

Notes: 1) Class 1M laser products that failed condition 1 of table 10. Not required for Class 1M laser products that failed condition 2 of table 10.

2) Class 2M laser products that failed condition 1 of table 10. Not required for Class 2M laser products that failed condition 2 of table 10.

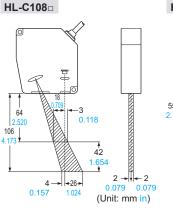
Remarks: This table is intended to provide a convenient summary of

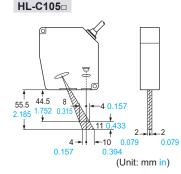
precautions. See text of this standard for complete precautions.

Refer to p.1027 for general precautions and p.1025~ for laser beam.

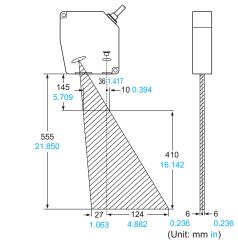
Mutual interference

· When installing 2 or more sensor heads side by side, mutual interference will not occur if the laser spots from other sensor heads do not fall within the shaded areas of the sensor head in the figure below. Multiple sensor heads must be installed in a manner such that laser spots from other sensor heads will be prevented from falling within these shaded areas. When two sensor heads are connected to a controller and used, the measures described below are not required since the mutual interference prevention function can be used.









Functional description

Sensor head

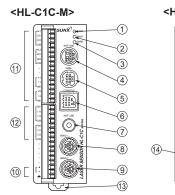


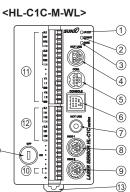
	Description	Function
1	Laser emission indicator (Green LED)	Lights up during laser emission or immediately before laser emission.
2	Measuring range indicator (Yellow LED)	Blinks within the measuring range and lights up when near the measurement center distance.
3	Warning label	Shows the laser emission position.

PRECAUTIONS FOR PROPER USE

Functional description

Controller





	Description	Function
1	Laser emission indicator (Green LED)	Lights up during laser emission from sensor head 1 or sensor head 2, or immediately before laser emission.
2	BRIGHT indicator (Red LED)	Lights up upon disabled measurement due to excessive light at sensor head 1 or 2.
3	DARK indicator (Red LED)	Lights up upon disabled measurement due to insufficient light at sensor head 1 or 2.
4		Cannot be used. This port is for adjustment at the factory before shipping.
5	COM. port	Used for RS-232C communications with a personal computer.
6	Connector for compact console	This enables measurement values to be displayed using the compact console and connection of the compact console exclusive connection cable when setting each setting.
1		Cannot be used. This port is for adjustment at the factory before shipping.
8	Sensor head 1 connector	The controller operates the sensor head connected to this connector as sensor head 1.
9	Sensor head 2 connector	The controller operates the sensor head connected to this connector as sensor head 2.
10	Power supply terminal	Supplies 24 V DC. There are power supply terminals on input terminal block.
(1)	External output terminal	
(12)	External input terminal	
(13)	DIN rail mounting hook	Can be mounted on a 35 mm 1.378 in width DIN rail quickly.
14	Key switch	Turning on the key switch starts up the controller. Please take out the key when it is not being used.

Functions

Function	Details
Data buffering function	 It is possible to accumulate data up to 48,000 data into a controller temporarily in order to capture measurement data into a PC. All the accumulated data can be captured into the PC with HL-C1AiM. Used for reading and storing all data including the verification of measurement data when introduced as well as all post-measurement data.
Hold function	 NORM. (no hold): Outputs the amount of displacement from the measurement center distance in real time. Ordinarily, this mode is used. P-P: This mode holds and outputs the difference between the maximum value and the minimum value. It is used for vibration measurements or eccentricity. PEAK: Holds and outputs the maximum measurement value. VALLEY : Holds and outputs the minimum measurement value.

Refer to p.1	027 for general precautions and p.1025~ for laser beam.	FIBER SENSORS			
Function	Details	LASER SENSORS			
	The measurement value and analog output at the timing of zero	PHOTO- ELECTRIC SENSORS			
Zero set function	setting are forcibly reset to zero. Use this function to reset the measurement value of the reference object to zero and measure the displacement amount or make a judgment of the upper or lower limit.				
Timing function	The judgment outputs (O1 and O2) immediately before the mode selection, measurement value and analog				
(excluding HL-C1C-M-WL)	output are held in the timing input mode. Laser emission can be halted or continued according to a setting. Add the input in other than the measurement or judgment state to aligning upper end of the setting.	SAFETY COMPONENTS			
Remote interlock function	 eliminate unnecessary output changes or laser radiation. This function stops laser radiation. Turning on the remote interlock input maintains the judgment output and then either holds values measurement values and analog outputs to the 	PRESSURE			
[HL-C1C-M-WL only]	values just obtained or it outputs the fixed values.	INDUCTIVE PROXIMITY SENSORS			
Display hold function	 Only the measurement value displayed on the compact console is held. Use this function to read a momentary measurement value. 	PARTICULAR USE SENSORS			
	In cases where objects with a low reflected light amount, such as black rubber, are measured, stable measurements can be taken	SENSOR OPTIONS			
Switching functions for	by extending the sampling rate and enabling a sufficient amount of light to be picked up by the sensor. If the sampling rate is short and not enough light can be picked up, the sensor enters the alarm	WIRE- SAVING SYSTEMS			
sampling rate	state, so switch the sampling rate to a longer duration setting. The sampling rate can be switched among 7 different rates. (100 µs / 144 µs / 200 µs / 255 µs / 332 µs / 498 µs / 1,000 µs)	MEASURE- MENT SENSORS			
	This function enables the unit to perform the following calculations: <calculation formulas="" independent="" measurements="" performing="" when=""></calculation>	STATIC CONTROL DEVICES			
Calculation function	L1 + K1A: normal output state L2 + K2B: normal output state L1 - K1A: reverses the polarity of the measured value L2 - K2B: reverses the polarity of the measured value <calculation calculation="" formulas="" measurements="" performing="" when=""> L + K (A + B): addition L - K (A + B): used when measuring thickness L + K (A - B): used when measuring level differences L - K (A - B): used when reversing the polarity of a subtraction output A: the value measured by sensor head 1 B: the value measured by sensor head 2 L: the amount of offset for the measured value K: the coefficient used to adjust the ratio of displacement changes</calculation>				
Switching functions for measurement mode	 The measurement mode (diffuse reflective / specular reflective) can be switched between these two modes, in accordance with the sensor head selected, based on the measurement object. Diffuse reflective mode: used when measuring without a mirror surface or not transparent. Specular reflective mode: used when measuring a substance with a mirror surface or that is transparent. When in specular reflective mode, the measurement object can be selected from the following options: Standard: used when measuring the mirror surfaces of opaque substance such as metal, etc. Front: used when measuring the surface of transparent substance such as glass, etc. Rear: used when measuring the rear surface of transparent substance such as glass, etc. The measurement conter distance is shifted. Thickness: used when measuring the thickness of transparent substance such as glass. The refraction angle is compensated to 1.55. There is a limitation in measurable thickness. Thickness measurement guidelines for common glass sheets: General-purpose model – thicknesses 1.2 mm 0.047 in or more High precision model – thicknesses 0.5 mm 0.020 in or more	Guide Laser Displacement HL-C2 HL-C1 LM10 Magnetic Displacement GP-X GP-A Collimated Beam Sensors HL-T1 LA-300 LA Other Products			
Low-pass filter function	 For example, if the surface conditions of a metal object cause noise that interferes with accurate measurement, the use of the low-pass filter function will reduce the effects of noise and allow for the stable measurement of displacement. 9 independent cutoff frequencies can be selected, OFF or ranging from 10 to 2,000 Hz. 				

Magnetic Displacement GP-X GP-A

Collimated Beam Sensors

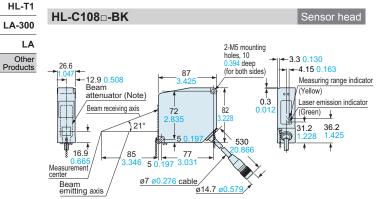
Functions

SENSORS						
PHOTO- ELECTRIC SENSORS	Function	Details				
MICRO PHOTO- ELECTRIC SENSORS AREA SENSORS SAFETY COMPONENTS PRESSURE SENSORS	High-pass filter function	 If joints or grooves are being measured in the midst of great changes such as runout or inclination in an eccentric rotating object etc., this setting minimizes the effects of gradual changes and makes it possible to detect joints or grooves. 9 independent cutoff frequencies can be selected, OFF or ranging from 10 to 2,000 Hz. 				
PROXIMITY SENSORS PARTICULAR USE SENSORS SENSOR OPTIONS WIRE-	Switching function for average number of samples	 If the measured values are subject to rapid fluctuation, then increasing the average number of samples will allow the unit to compensale for these fluctuations, enabling stable measurements to be obtained. The average number of samples can be selected from among 16 steps, ranging from OFF to 32,768 times. 				
MIRE- SAVING SYSTEMS MEASURE- MENT SENSORS STATIC CONTROL DEVICES LASER MARKERS		The judgment output O1, O2 (NC) can be selected from the four types listed in the table below. Logical output and judgment Display Upper limit value (HIGH) Lower limit value (LOW) Lower limit value (LOW) Cover limit value (LO				
Selection Guide	Judgment output selection function	O1 LOW Core upper limit setting is ignored. O1 LOW Core Select to distinguish between the upper limit and lower limit when the measurement value exceeds either limit. O1 LOW or HIGH Core Select to distinguish between the upper limit and lower limit. O1 LOW or HIGH Core Select to distinguish between the upper limit and lower limit. O1 LOW or HIGH Core Select to distinguish between deviation from the upper or lower limit value and containment in the range. Use this for OK / NG judgment.				
Laser Displacement HL-C2 HL-C1 LM10		O1 O2 LOGIC Open Close Open Close Open Close Open Close Open Close Open Close Open Close Open Close				
Magnetic Displacement GP-X		* The output state is the state in which the terminal is open. (NC)				

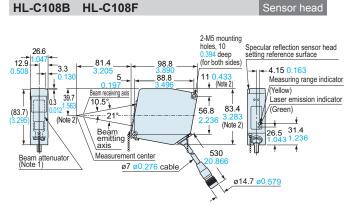
Function	Details
Hysteresis setting function	 Optional hysteresis settings can be selected for both the upper and lower limits.
Analog output setting function	• This function causes the output to correspond to the measurement value wanted at an analog output of +5 V (20 mA) and at -5 V (4 mA). It can be used for scaling of the analog output or for making the output greater or smaller, etc. When this function is used, the analog output corresponding to measurement values ranging between, for example, 70 to 90 mm 2.756 to 3.543 in, can be assigned to outputs ranging from -5 V (for 70 mm 2.756 in) to +5 V (for 90 mm 3.543 in).
Analog Output switching function during alarm	 You can switch between the data having been output immediately before and a fixed value as an analog output issued when measurement is disabled (with an alarm output) due to an excessive or insufficient amount of light or deviation from the range. When the fixed value setting is selected, either the maximum value (voltage output: +10.9 V, current output: 29.5 mA) or minimum value (voltage output: -10.9 V, current output: 0 mA) of the analog output is issued during an alarm.
Input selection function	 The timing signal at the input terminal functions as an input upon a short circuit by default setting. Use this function to activate the input upon an open circuit.
Calibration function	 Measurement errors may occur due to the color, material or surface condition of the object being measured. These differences can be compensated for through calibration. The calibration function allows the span and shift to be set for each sensor head. There are two ways to set these values. One is to conduct auto setting by moving a piece of the object past sensors and the other is to input previously measured values directly.
Display light received function	 This function displays the peak level of light received at the measuring point. The usage of this function when installing sensor heads allows the optimum marginal increment to be used as the level of light received for measurement.
Save function	 This function saves all setting data except for the timing input state and display hold state.

Refer to p.1027 for general precautions and p.1025~ for laser beam.

DIMENSIONS (Unit: mm in) The CAD data in the dimensions can be downloaded from the SUNX website: http://www.sunx.com



Note: There is not beam attenuator on IEC / JIS standards conforming type.



Notes: 1) There is not beam attenuator on IEC / JIS standards conforming type.

2) Figure shows standard installation level dimensions.

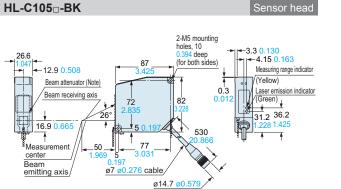
USE SENSORS

SENSOR OPTIONS

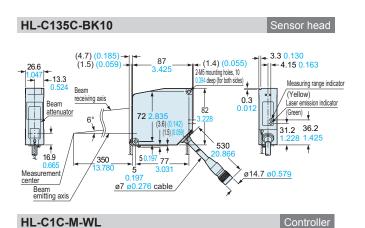
WIRE-SAVING SYSTEMS

STATIC CONTROL DEVICES

LASER MARKERS



Note: There is not beam attenuator on IEC / JIS standards conforming type.



(5.5)

(10)

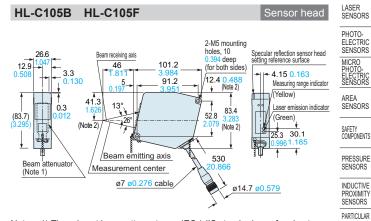
▲ (1) 5.5 <mark>(0.3</mark>

0 217

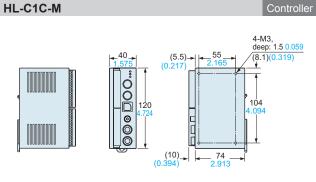
55

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2 913



Notes: 1) There is not beam attenuator on IEC / JIS standards conforming type. 2) Figure shows standard installation level dimensions.



HL-C1DP-E(-WL)

4-M3, 1.5 0.059 deep

(8.1)<mark>(0.319)</mark>

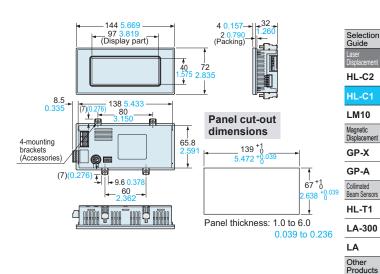
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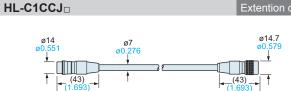
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Compact console





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3 0.118

Length L			
Model No.	Length L		
HL-C1CCJ2	2,000 78.740		
HL-C1CCJ5	5,000 196.850		
HL-C1CCJ10	10,000 393.700		
HL-C1CCJ20	20,000 787.400		
HL-C1CCJ30	30,000 1181.100		

DIMENSIONS (Unit: mm in) The CAD data in the dimensions can be downloaded from the SUNX website: http://www.sunx.com